

Chaos and Shadowing Around a Homoclinic Tube

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ABSTRACT. Let F be a C^3 diffeomorphism on a Banach space B . F has a homoclinic tube asymptotic to an invariant manifold. Around the homoclinic tube, Bernoulli shift dynamics of submanifolds is established through shadowing lemma. This work removes an uncheckable condition of Silnikov [Equation (11), page 625 of L. P. Silnikov, Soviet Math. Dokl., vol.9, no.3, (1968), 624-628]. Also, the result of Silnikov does not imply Bernoulli shift dynamics of a single map, rather only provides a labeling of all invariant tubes around the homoclinic tube. The work of Silnikov was done in \mathbb{R}^n , and the current work is done in a Banach space.

1. Introduction

In [1], Silnikov introduced the concept of a homoclinic tube which can be obtained through a transversal intersection of the center-unstable and center-stable manifolds of a normally hyperbolic invariant manifold under a map in \mathbb{R}^n . Intuitively speaking, a homoclinic tube can be regarded as a homoclinic orbit on which points are replaced by submanifolds. Under certain assumption [Equation (11) on page 625 of [1]] which is uncheckable, all the invariant tubes in the neighborhood of the homoclinic tube can be labeled symbolically. Such a symbolic labeling does not imply Bernoulli shift of a single map. The result was proved through a contraction map argument on a sequence of metric spaces. In the current article, we will adopt a different approach developed in [2]. We will establish Bernoulli shift dynamics of submanifolds through shadowing lemma. The uncheckable assumption of Silnikov is removed. We will work in a Banach space, while Silnikov worked in \mathbb{R}^n .

Especially for high dimensional systems, homoclinic tubes are more dominant structures than homoclinic orbits. In fact, the invariant manifold that the homoclinic tube is asymptotic to, can contain smaller scale chaotic dynamics as discussed in [3] [4]. Although structures in a neighborhood of a homoclinic orbit have been extensively and intensively investigated, structures around a homoclinic tube have not been well studied [1] [3] [4]. I believe that homoclinic tubes will play an important role in the theory of chaos in Hamiltonian partial differential equations.

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The article is organized as follows: section 1 is the introduction, section 2 contains the setup and definitions, section 3 deals with Fenichel fiber coordinates and a λ -lemma, and section 4 deals with shadowing lemma and chaos.

2. The Setup and Definitions

The setup is as follows:

- **(A1).** Let B be a Banach space on which a C^3 -diffeomorphism F is defined. There is a normally (transversally) hyperbolic invariant C^3 submanifold S . Let W^{cu} and W^{cs} be the C^3 center-unstable and center-stable manifolds of S . There exist a C^2 invariant family of C^3 unstable Fenichel fibers $\{\mathcal{F}^u(q) : q \in S\}$ and a C^2 invariant family of C^3 stable Fenichel fibers $\{\mathcal{F}^s(q) : q \in S\}$ inside W^{cu} and W^{cs} respectively, such that

$$W^{cu} = \bigcup_{q \in S} \mathcal{F}^u(q), W^{cs} = \bigcup_{q \in S} \mathcal{F}^s(q).$$

There are positive constants κ and C such that

$$\begin{aligned} \|F^{-n}(q^-) - F^{-n}(q)\| &\leq Ce^{-\kappa n} \|q^- - q\|, \quad \forall n \in \mathbb{Z}^+, \quad \forall q \in S, \quad \forall q^- \in \mathcal{F}^u(q), \\ \|F^n(q^+) - F^n(q)\| &\leq Ce^{-\kappa n} \|q^+ - q\|, \quad \forall n \in \mathbb{Z}^+, \quad \forall q \in S, \quad \forall q^+ \in \mathcal{F}^s(q), \\ \|F^n(q_1) - F^n(q_2)\| &\leq Ce^{\kappa_1 |n|} \|q_1 - q_2\|, \quad \forall n \in \mathbb{Z}, \quad \forall q_1, q_2 \in S, \end{aligned}$$

where $\kappa_1 \ll \kappa$, for example, $\kappa_1 < \kappa/300$. W^{cu} and W^{cs} intersect along an isolated transversal homoclinic tube ξ asymptotic to S . $\xi = (\cdots S_{-1} S_0 S_1 \cdots)$ where $S_j = F^j S_0$, $\forall j \in \mathbb{Z}$, and S_0 is C^3 . $\forall j \in \mathbb{Z}$ and $\forall q_j \in S_j$, q_j is on a unique stable fiber $\mathcal{F}^s(q_+)$, $q_+ \in S$, and a unique unstable fiber $\mathcal{F}^u(q_-)$, $q_- \in S$. We denote such correspondences by φ_j^+ and φ_j^- respectively, $\varphi_j^\pm(S) = S_j$. φ_j^\pm are C^2 diffeomorphisms. Let

$$\|\varphi_j^\pm - \text{id}\|_{C^1} = \sup_{q \in S} \{\max\{\|\varphi_j^\pm(q) - q\|, \|D\varphi_j^\pm(q) - \text{id}\|\}\}$$

where id is the identity map and $D\varphi_j^\pm$ denotes the differential of φ_j^\pm . As $j \rightarrow +\infty$,

$$\|\varphi_j^+ - \text{id}\|_{C^1} \rightarrow 0.$$

As $j \rightarrow -\infty$,

$$\|\varphi_j^- - \text{id}\|_{C^1} \rightarrow 0.$$

Let

$$\begin{aligned} \theta = \inf_{u, v, w, q_j \in S_j, j \in \mathbb{Z}} & \left\{ \min\{\|u - v\|, \|v - w\|, \|w - u\|\} \mid u \in T_{q_j} \mathcal{F}^u(q_-), \right. \\ & \left. v \in T_{q_j} \mathcal{F}^s(q_+), w \in T_{q_j} S_j, \|u\| = \|v\| = \|w\| = 1 \right\}, \end{aligned}$$

where T_{q_j} indicates the tangent space at q_j . In this article, transversality always implies that such angle θ is positive.

- **(A2).** Let Ω be a neighborhood of S . Then there exists a $J > 0$ such that $S_j \subset \Omega$, $\forall |j| \geq J$. Let

$$d = \inf_{q \in S_j \cup S, |j| \geq J} \{\text{distance}\{q, \partial\Omega\}\},$$

then $d > 0$. Let Ω_j be a neighborhood of $S_j, \forall |j| < J$,

$$d_j = \inf_{q \in S_j} \{ \text{distance } \{q, \partial\Omega_j\} \} ,$$

then $d_j > 0$. The collection $B_\xi = \{\Omega, \Omega_j \mid |j| < J\}$ is called a tubular neighborhood of $\xi \cup S$. For any $0 < n < \infty$, there exists such a tubular neighborhood B_ξ of $\xi \cup S$, such that for any $q_1 \in B_\xi$ there is a $q \in \xi \cup S$, q_1 and q belong to the same Ω or $\Omega_j \mid |j| < J$,

$$\|D^\ell F^{\pm n}(q_1) - D^\ell F^{\pm n}(q)\| < 1, \quad (\ell = 1, 2) .$$

Moreover,

$$\max_{+, -} \sup_{q \in \xi \cup S} \|D^2 F^{\pm n}(q)\| < \infty .$$

Let

$$\Lambda_\ell = \max_{+, -} \sup_{q \in B_\xi} \|D^\ell F^{\pm n}(q)\| < \infty, \quad (\ell = 1, 2) .$$

If $\xi \cup S$ is compact, then assumption **(A2)** holds [2]. Next we will introduce a pseudo-invariant tube. An invariant tube is a sequence of submanifolds $\{B_j\}_{j \in \mathbb{Z}}$ such that

$$F(B_j) = B_{j+1}, \quad F^{-1}(B_j) = B_{j-1}, \quad \forall j \in \mathbb{Z} .$$

DEFINITION 2.1. Segment-0 is defined as the finite sequence of $2N+1$ S 's

$$\eta_0 = (S \cdots S) ,$$

and Segment-1 is defined as the finite sequence

$$\eta_1 = (S_{-N} S_{-N+1} \cdots S_0 \cdots S_{N-1} S_N) ,$$

where N is a large positive integer.

DEFINITION 2.2. Let Σ be a set that consists of elements of the doubly infinite sequence form:

$$a = (\cdots a_{-2} a_{-1} a_0, a_1 a_2 \cdots),$$

where $a_k \in \{0, 1\}, k \in \mathbb{Z}$. We introduce a topology in Σ by taking as neighborhood basis of

$$a^* = (\cdots a_{-2}^* a_{-1}^* a_0^*, a_1^* a_2^* \cdots),$$

the set

$$\mathcal{A}_j = \{a \in \Sigma \mid a_k = a_k^* (|k| < j)\}$$

for $j = 1, 2, \cdots$. This makes Σ a topological space. The Bernoulli shift automorphism χ is defined on Σ by

$$\chi : \Sigma \mapsto \Sigma, \quad \forall a \in \Sigma, \quad \chi(a) = b, \quad \text{where } b_k = a_{k+1}.$$

The Bernoulli shift automorphism χ exhibits sensitive dependence on initial conditions, which is a hallmark of chaos.

For any $\delta > 0$, there exists $N > 0$, such that

$$\|\varphi_j^+ - \text{id}\|_{C^1} < \delta, \quad \|\varphi_{-j}^- - \text{id}\|_{C^1} < \delta, \quad \forall j \geq N ,$$

by assumption **(A1)**.

DEFINITION 2.3. To each $a_k \in \{0, 1\}$, we associate the Segment- a_k , η_{a_k} . Then each doubly infinite sequence

$$a = (\cdots a_{-2} a_{-1} a_0, a_1 a_2 \cdots)$$

is associated with a δ -pseudo-invariant tube

$$\eta_a = (\cdots \eta_{a_{-2}} \eta_{a_{-1}} \eta_{a_0}, \eta_{a_1} \eta_{a_2} \cdots).$$

3. Fenichel Fiber Coordinates and a λ -Lemma

3.1. Fenichel Fiber Coordinates. We will introduce Fenichel fiber coordinates in a neighborhood of S . For any $\theta \in S$, let

$$E^u(\theta) = T_\theta \mathcal{F}^u(\theta), \quad E^c(\theta) = T_\theta S, \quad E^s(\theta) = T_\theta \mathcal{F}^s(\theta),$$

where T_θ indicates the tangent space at θ . E^u and E^s provide a coordinate system for a neighborhood of S , that is, any point in this neighborhood has a unique coordinate

$$(\tilde{v}^s, \tilde{\theta}, \tilde{v}^u), \quad \tilde{v}^s \in E^s(\tilde{\theta}), \quad \tilde{v}^u \in E^u(\tilde{\theta}), \quad \tilde{\theta} \in S.$$

Fenichel fibers provide another coordinate system for the neighborhood of S . For any $\theta \in S$, the Fenichel fibers $\mathcal{F}^s(\theta)$ and $\mathcal{F}^u(\theta)$ have the expressions

$$\begin{cases} \tilde{v}^s = v^s, \\ \tilde{\theta} = \theta + \Theta_s(v^s, \theta), \\ \tilde{v}^u = V_s(v^s, \theta), \end{cases} \quad \text{and} \quad \begin{cases} \tilde{v}^u = v^u, \\ \tilde{\theta} = \theta + \Theta_u(v^u, \theta), \\ \tilde{v}^s = V_u(v^u, \theta), \end{cases}$$

where v^s and v^u are the parameters parametrizing $\mathcal{F}^s(\theta)$ and $\mathcal{F}^u(\theta)$,

$$\Theta_z(0, \theta) = \frac{\partial}{\partial v^z} \Theta(0, \theta) = V_z(0, \theta) = \frac{\partial}{\partial v^z} V_z(0, \theta) = 0, \quad z = u, s;$$

and $\Theta_z(v^z, \theta)$ and $V_z(v^z, \theta)$ ($z = u, s$) are C^3 in v^z and C^2 in θ . The coordinate transformation from (v^s, θ, v^u) to $(\tilde{v}^s, \tilde{\theta}, \tilde{v}^u)$

$$\begin{cases} \tilde{v}^s = v^s + V_u(v^u, \theta), \\ \tilde{\theta} = \theta + \Theta_u(v^u, \theta) + \Theta_s(v^s, \theta), \\ \tilde{v}^u = v^u + V_s(v^s, \theta), \end{cases}$$

is a C^2 diffeomorphism. In terms of the Fenichel coordinate (v^s, θ, v^u) , the Fenichel fibers coincide with their tangent spaces. From now on, we always work with the Fenichel coordinate (v^s, θ, v^u) .

3.2. λ -Lemma. $\forall j \in \mathbb{Z}$ and $\forall q_j \in S_j$, q_j is on a unique stable fiber $\mathcal{F}^s(q_+)$, $q_+ \in S$, and a unique unstable fiber $\mathcal{F}^u(q_-)$, $q_- \in S$. Let

$$E^u(q_j) = T_{q_j} \mathcal{F}^u(q_-), \quad E^c(q_j) = T_{q_j} S_j, \quad E^s(q_j) = T_{q_j} \mathcal{F}^s(q_+).$$

By assumption **(A1)**, $E^u(q_j)$, $E^c(q_j)$, and $E^s(q_j)$ are C^2 in $q_j \in S_j$.

LEMMA 3.1 (λ -Lemma). *For any $\epsilon > 0$, there exists a $J > 0$ such that*

- (1) *When $j \geq J$, $E^u(q_j) \oplus E^c(q_j)$ is ϵ -close to $E^u(q_+) \oplus E^c(q_+)$.*
- (2) *When $j \leq -J$, $E^s(q_j) \oplus E^c(q_j)$ is ϵ -close to $E^s(q_-) \oplus E^c(q_-)$.*

Proof: When j (> 0) is large enough, q_j is in a neighborhood of S where $\mathcal{F}^s(q_+) = E^s(q_+)$. Let $v_1 \in E^u(q_j) \oplus E^c(q_j)$, $\|v_1\| = 1$. One can represent v_1 in the frame $(E^s(q_+), E^u(q_+) \oplus E^c(q_+))$,

$$v_1 = (v_1^s, v_1^{uc}) .$$

Let $\lambda_1 = \|v_1^s\|/\|v_1^{uc}\|$. By assumption **(A1)**, transversality implies that λ_1 has an absolute upper bound. The rest of the argument is the same with that in [2]. Q.E.D.

3.3. A Rectification. Next we conduct a rectification in a neighborhood of S , which is necessary for graph transform argument later on. When j (> 0) is large enough, q_j is in a neighborhood of S where $\mathcal{F}^s(q_+) = E^s(q_+)$. Thus $E^s(q_j) = E^s(q_+)$. For any $\tilde{v}^u \in E^u(q_+)$, $\|\tilde{v}^u\| = 1$, \tilde{v}^u has the representation in the frame $(E^s(q_j), E^u(q_j) \oplus E^c(q_j))$,

$$\tilde{v}^u = v^s + v^{uc} .$$

All such v^{uc} 's span the projection $\tilde{E}^u(q_j)$ of $E^u(q_+)$ onto $E^u(q_j) \oplus E^c(q_j)$. $E^u(q_j) \oplus E^c(q_j)$ is C^2 in q_j . Shifting $E^u(q_+)$, $E^c(q_+)$, and $E^s(q_+)$ to q_j , they are also C^2 in q_j . Representing $E^u(q_j) \oplus E^c(q_j)$ in the frame $(E^u(q_+), E^c(q_+), E^s(q_+))$, $\tilde{E}^u(q_j)$ can be obtained from $E^u(q_j) \oplus E^c(q_j)$ by restricting $\theta = 0$, where θ coordinatizes $E^c(q_+)$. Thus $\tilde{E}^u(q_j)$ is also C^2 in q_j . The rectification amounts to replacing $E^u(q_j)$ by $\tilde{E}^u(q_j)$. We will use the same notation $E^u(q_j)$. Similarly, when j (> 0) is large enough, one can rectify $E^s(q_{-j})$ inside $E^s(q_{-j}) \oplus E^c(q_{-j})$.

4. Shadowing Lemma and Chaos

Let η_a be a δ -pseudo-invariant tube defined in Definition 2.3,

$$\eta_a = (\cdots \tilde{S}_{-1} \tilde{S}_0 \tilde{S}_1 \cdots)$$

where $\tilde{S}_j = S_k$ or S ; $j, k \in \mathbb{Z}$. Denote by \hat{E} the transversal bundle

$$\hat{E} = \{(q, E^u(q), E^s(q)) \mid q \in \eta_a\},$$

which serves as a coordinate system around η_a , with the coordinate denoted by

$$(q, x^u, x^s), \quad \text{where } q \in \eta_a, \quad x^u \in E^u(q), \quad x^s \in E^s(q).$$

In this coordinate system, the map F^n has the representation

$$F^n(q, x^u, x^s) = (f(q, x^u, x^s), g^u(q, x^u, x^s), g^s(q, x^u, x^s)),$$

where n is a large positive integer. If $q \in \tilde{S}_j$, then $f(q, x^u, x^s) \in \tilde{S}_{j+n}$.

LEMMA 4.1. $\forall \mu > 0$, fix a n large enough, and fix a ϵ small enough, if δ is sufficiently small, then

$$\begin{aligned} (\Lambda_1)^k \Pi_3^s &< \frac{1}{2}, \quad (0 \leq k \leq 2), \quad \Pi_\ell^s < \mu, \quad (\ell = 1, 2), \\ (\Lambda_1)^k \hat{\Pi}_2^u &< \frac{1}{2}, \quad (0 \leq k \leq 2), \quad \Pi_\ell^u < \mu, \quad (\ell = 1, 3), \end{aligned}$$

where $\|x^u\| \leq \epsilon$, $\|x^s\| \leq \epsilon$, $D_1 = D_q$, $D_2 = D_{x^u}$, $D_3 = D_{x^s}$, and

$$\begin{aligned}\Pi_\ell^s &= \sup_{q, x^u, x^s} \|D_\ell g^s(q, x^u, x^s)\|, \quad (\ell = 1, 2, 3), \\ \Pi_\ell^u &= \sup_{q, x^u, x^s} \|D_\ell g^u(q, x^u, x^s)\|, \quad (\ell = 1, 2, 3), \\ \widehat{\Pi}_2^u &= \sup_{q, x^u, x^s} \|\{D_2 g^u(q, x^u, x^s)\}^{-1}\|.\end{aligned}$$

Proof: The proof of this lemma follows from assumptions **(A1)** and **(A2)**, and the fact that along Segment-0 and Segment-1, the center-unstable and center-stable bundles $E^u(q) \oplus E^c(q)$ and $E^s(q) \oplus E^c(q)$ are invariant under the linearized flow [2]. Q.E.D.

Let Γ_ϵ be the space of sections of \widehat{E} :

$$\Gamma_\epsilon = \{\sigma \mid \sigma(q) = (q, x^u(q), x^s(q)), q \in \eta_a, \|x^u(q)\| \leq \epsilon, \|x^s(q)\| \leq \epsilon\}.$$

We define the C^0 norm of $\sigma \in \Gamma_\epsilon$ as

$$\|\sigma\|_{C^0} = \max\{\sup_{q \in \eta_a} \|x^u(q)\|, \sup_{q \in \eta_a} \|x^s(q)\|\}.$$

Then we define a Lipschitz semi-norm on Γ_ϵ :

$$\text{Lip}\{\sigma\} = \max\left\{\sup_{\|q_1 - q_2\| \leq \Delta} \frac{\|x^u(q_1) - x^u(q_2)\|}{\|q_1 - q_2\|}, \sup_{\|q_1 - q_2\| \leq \Delta} \frac{\|x^s(q_1) - x^s(q_2)\|}{\|q_1 - q_2\|}\right\}$$

for some small fixed $\Delta > 0$. Let $\Gamma_{\epsilon, \gamma}$ be a subset of Γ_ϵ ,

$$\Gamma_{\epsilon, \gamma} = \{\sigma \in \Gamma_\epsilon \mid \text{Lip}\{\sigma\} \leq \gamma\}.$$

For any $\sigma \in \Gamma_{\epsilon, \gamma}$,

$$\sigma(q) = (q, x^u(q), x^s(q)), \quad q \in \eta_a,$$

we define the *graph transform* G as follows:

$$(4.1) \quad (G\sigma)(q) = (q, x_1^u(q), x_1^s(q)),$$

where

$$\begin{aligned}f(q^-, x^u(q^-), x^s(q^-)) &= q, \\ g^s(q^-, x^u(q^-), x^s(q^-)) &= x_1^s(q), \\ f(q, x_1^u(q), x^s(q)) &= q^+, \\ g^u(q, x_1^u(q), x^s(q)) &= x^u(q^+),\end{aligned}$$

for some q^- and q^+ .

THEOREM 4.2. *The graph transform G is a contraction map on $\Gamma_{\epsilon, \gamma}$. The graph of the fixed point σ^* of G is an invariant tube under F .*

Proof: The proof of this theorem is similar to that given in details in [2]. Q.E.D.

$\text{Graph}\{\sigma^*\}$ is the invariant tube that ϵ -shadows the δ -pseudo-invariant tube η_a . Let S^* be the element of $\text{Graph}\{\sigma^*\}$, that shadows the mid-element of η_a , which is either S_0 or S . Such S^* 's for all η_a forms a set Ξ of submanifolds. It is obvious that the following theorem holds.

THEOREM 4.3 (Chaos Theorem). *The set Ξ of submanifolds is invariant under the map F^{2N+1} . The action of F^{2N+1} on Ξ is topologically conjugate to the action of the Bernoulli shift automorphism χ on Σ . That is, there exists a homeomorphism $\phi : \Sigma \mapsto \Xi$ such that the following diagram commutes:*

$$\begin{array}{ccc} \Sigma & \xrightarrow{\phi} & \Xi \\ \chi \downarrow & & \downarrow F^{2N+1} \\ \Sigma & \xrightarrow{\phi} & \Xi \end{array}$$

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